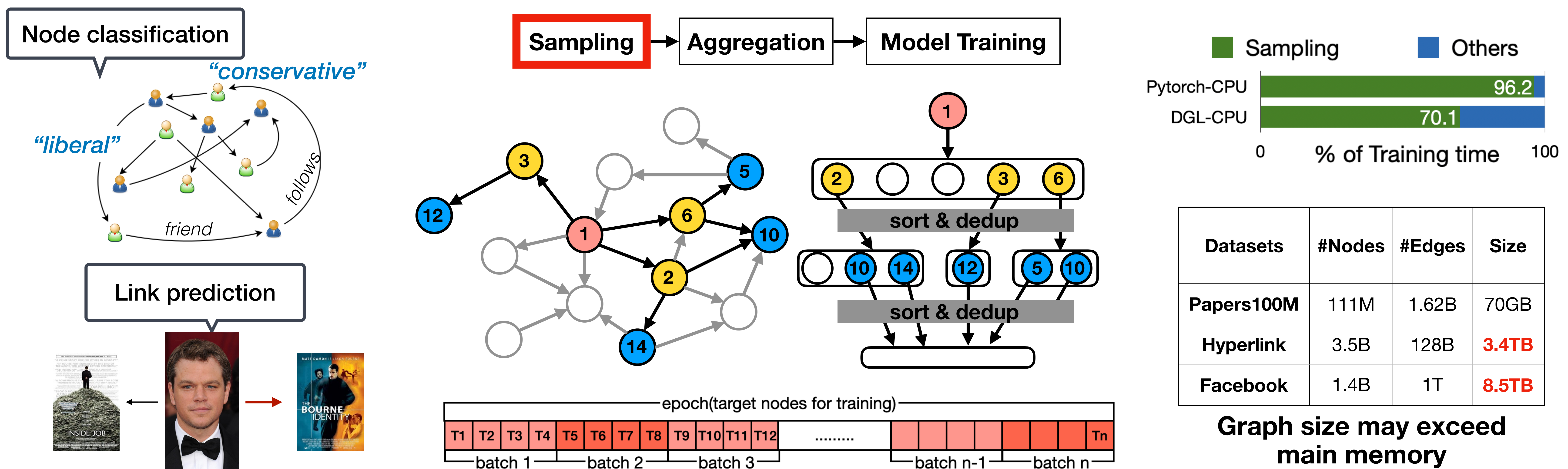


Graph Representation Learning and GNN Sampling



Current Approaches and Limitations

CPU-based (MariusGNN, Ginex)

- Unnecessary I/O from loading full neighborhoods into memory
- Lower computation power than GPU
- High data movement overhead between memory and SSD

GPU-based (NextDoor, gSampler)

- Constrained GPU memory
- Sampling competes with other tasks for GPU resources
- High computation cost

SSD-based (In-situ SmartSSD, FlashGNN)

- Difficult to adopt widely across different hardware configurations
- Limited bandwidth compared to main memory



My proposal: Leverage modern storage APIs and high-bandwidth SSDs to perform sampling on larger-than-memory graphs

CPU-Based Sampling System Accelerated by io_uring

- How to minimize data movement between SSD and CPU?
- How to integrate io_uring to GNN Sampling?
- How to implement multi-threading to maximize CPU utilization?
- How to take the advantage of asynchronous I/O?

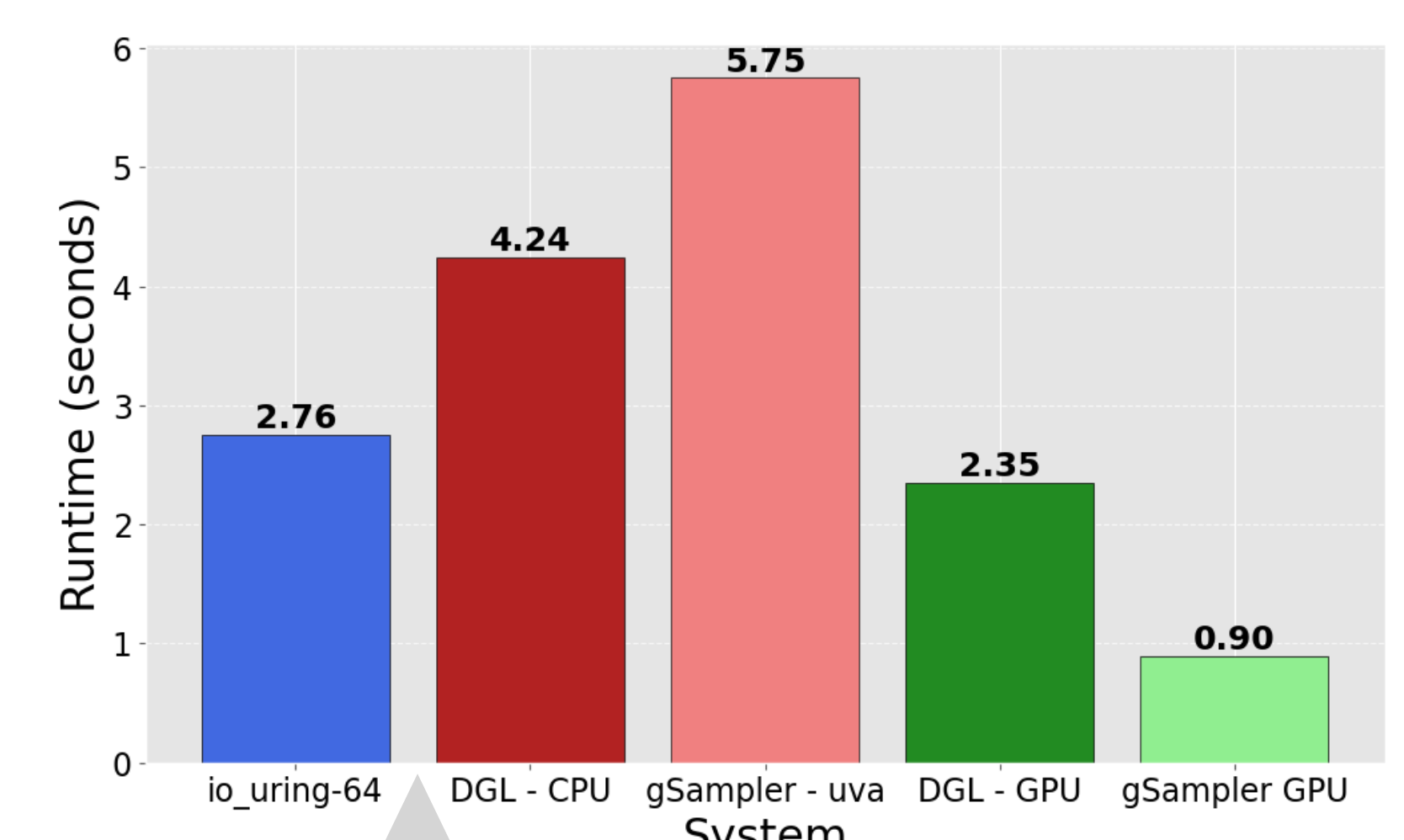
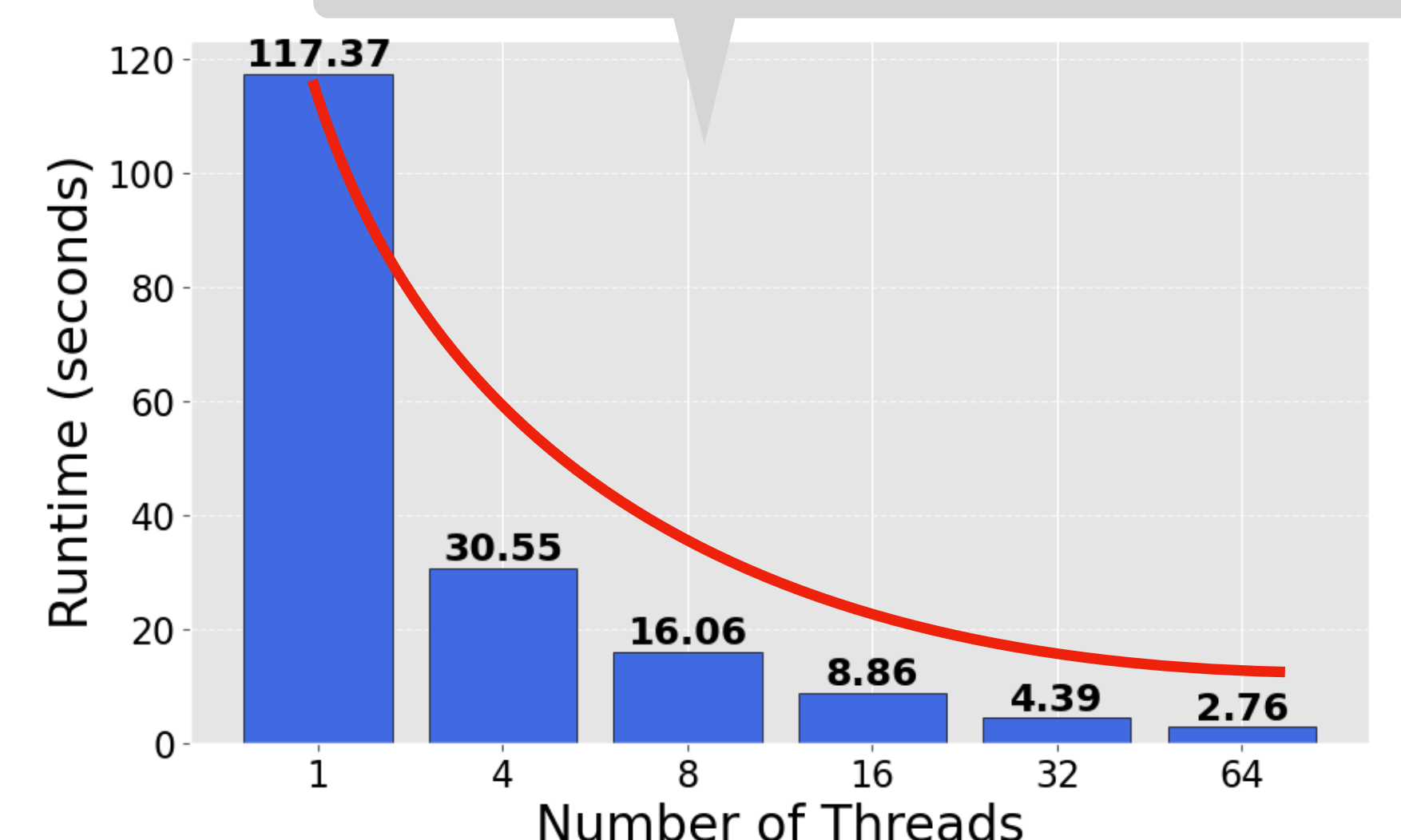
Create two indexes to efficiently select neighbor offsets, allowing direct access to sampled neighbors without loading all neighbors from disk

Batch I/O requests to read neighbors

Equally distribute batches to threads. Each thread works in parallel with their own io_uring buffers without interrupting each other

While CQ is polling completions, we prepare and load the next I/O batch into the SQ, submitting it once the previous batch is done

performance scales almost linearly with thread count



Sampling billion-edge graph

- 1.5x faster than baseline
- Comparable with GPU-based
- Can process larger-than-memory graphs

